

A quantum-inspired version of the nearest mean classifier

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Abstract We introduce a framework suitable for describing standard classification problems using the mathematical 2 language of quantum states. In particular, we provide a one-3 to-one correspondence between real objects and pure density Δ operators. This correspondence enables us: (1) to represent 5 the nearest mean classifier (NMC) in terms of quantum objects, (2) to introduce a quantum-inspired version of the NMC called quantum classifier (QC). By comparing the QC 8 with the NMC on different datasets, we show how the first classifier is able to provide additional information that can be 10 beneficial on a classical computer with respect to the second 11 classifier. 12

¹³ Keywords Bloch sphere · Quantum classifier · Non-

14 standard application of quantum formalism

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1 Introduction

Quantum machine learning aims at merging the methods 16 from quantum information processing and pattern recogni-17 tion to provide new solutions for problems in the areas of 18 pattern recognition and image understanding (Schuld et al. 19 2014a; Wittek 2014; Wiebe et al. 2015). In the first aspect, the 20 research in this area is focused on the application of the meth-21 ods of quantum information processing (Miszczak 2012) for 22 solving problems related to classification and clustering Tru-23 genberger (2002), Caraiman and Manta (2012). One of the 24 possible directions in this field is to provide a representa-25 tion of computational models using quantum mechanical 26 concepts. From the other perspective, the methods for classi-27 fication developed in computer engineering are used to find 28 solutions for problems such as quantum-state discrimination 29 (Helstrom 1976; Chefles 2000; Hayashi et al. 2005; Lu and 30 Braunstein 2014), which are tightly connected with the recent 31 developments in quantum cryptography. 32

Using quantum states for the purpose of representing patterns 33 is naturally motivated by the possibility of exploiting quan-34 tum algorithms to boost the computational intensive parts of 35 the classification process. In particular, it has been demon-36 strated that quantum algorithms can be used to improve the 37 time complexity of the k-nearest neighbor (kNN) method. 38 Using the algorithms presented in Wiebe et al. (2015), it is 39 possible to obtain polynomial reductions in query complex-40 ity in comparison with the corresponding classical algorithm. 41 Such an approach has been exploited by various authors. In 42 Tanaka and Tsuda (2008), the authors propose an extension of 43 Gaussian mixture models by using the statistical mechanics 44 point of view. In their approach, the probability density func-45 tions of conventional Gaussian mixture models are expressed 46 by density matrix representations. On the other hand, in 47 Ostaszewski et al. (2015), the authors utilize the quantum 48

representation of images to construct measurements used for 10 classification. Such approach might be particularly useful for 50 the physical implementation of the classification procedure 51 on quantum machines. 52

In the last few years, many efforts have been made to apply 53 the quantum formalism to non-microscopic contexts (Aerts 54 and D'Hooghe 2009; Aerts et al. 2013; Chiang et al. 2013; 55 Eisert et al. 1999: Nagel 1963: Nagy and Nagy 2016: Ohva 56 and Volovich 2011; Schwartz et al. 2005; Sozzo 2015; Stapp 57 1993) and to signal processing (Eldar and Oppenheim 2002). 58 Moreover, some attempts to connect quantum information to 59 pattern recognition can be found in Schuld et al. (2014a), 60 Schuld et al. (2014b), Schuld et al. (2014c). An exhaustive 61 survey and bibliography of the developments concerning the 62 applications of quantum computing in computational intel-63 ligence are provided in Manju and Nigam (2014), Wittek 64 (2014). Even if these results seem to suggest some possi-65 ble computational advantages of an approach of this sort, an 66 extensive and universally recognized treatment of the topic 67 is still missing (Schuld et al. 2014a; Lloyd et al. 2014, 2013). 68

Also, this paper is motivated by the idea of using quantum 69 formalism in a non-standard domain that consists in solving 70 classification problems on datasets of classical objects. The 71 main contribution of our work is the introduction of a new 72 framework to encode the classification process by means of 73 the mathematical language of density matrices (Beltrametti 74 et al. 2014b, a). We show that this representation leads to 75 two different developments: (i) It enables us to provide a 76 representation of the nearest mean classifier (NMC) in terms 77 of quantum objects; (ii) it can be used to introduce a quantum-78 inspired version of the NMC, that we call quantum classifier 79 (OC), which can be considered (similarly as the NMC) to 80 be a minimum distance classifier. This allows us a detailed 81 comparison between NMC and QC. In particular, we will 82 show that QC provides additional information about the data 83 distribution and, in different cases, an improvement in the 84 performance on a classical computer. 85

The paper is organized as follows. In Sect. 2, the basic 86 notions of quantum information and pattern recognition 87 are introduced. In Sect. 3, we formalize a correspondence 88 between arbitrary two-feature patterns and pure density oper-89 ators and we define the notion of *density pattern*. In Sect. 4, 90 we provide a representation of NMC by using density pat-91 terns and by the introduction of an ad hoc definition of the 92 distance between quantum states. Section 5 is devoted to 93 the description of a new quantum classifier QC that does 94 not have a classical counterpart in the standard classification 95 process. Numerical simulations for both QC and NMC are 96 presented, and particular benefits in favor of the first classifier 97 are exploited. In Sect. 6, a geometrical idea to generalize the 98 model to arbitrary *n*-feature patterns is proposed. Finally, 99 Sect. 7 presents concluding remarks and suggests further 100 developments. 101

2 Representing classical and quantum information 102 quantities 103

In the standard quantum information theory (Bennett and 104 Shor 1998; Shannon 1948), the states of physical systems are 105 described by unit vectors and their evolution is expressed in 106 terms of unitary matrices (i.e., quantum gates). However, this 107 representation can be applied for an ideal case only, because 108 it does not take into account some unavoidable physical 109 phenomena, such as interactions with the environment and 110 irreversible transformations. In the modern quantum infor-111 mation theory (Jaeger 2007, 2009; Wilde 2013), another 112 approach is adopted. The states of physical systems are 113 described by density operators-also called mixed states 114 (Aharonov et al. 1998; Chiara et al. 2004; Freytes et al. 115 2010)—and their evolution is described by quantum oper-116 ations. The space Ω_n of density operators for *n*-dimensional 117 system consists of positive semidefinite matrices with unit 118 trace. 119

A quantum state can be *pure* or *mixed*. We say that a state 120 of a physical system is pure if it represents "maximal" infor-121 mation about the system, i.e., information that cannot be 122 improved by further observations. A probabilistic mixture 123 of pure states is said to be a *mixed* state. Generally, both pure 124 and mixed states are represented by density operators that 125 are positive and Hermitian operators (with unitary trace) liv-126 ing in a *n*-dimensional complex Hilbert space \mathcal{H} . Formally, 127 a density operator ρ is pure iff $tr(\rho^2) = 1$ and it is mixed iff 128 $tr(\rho^2) < 1.$ 120

If we confine ourselves to the two-dimensional Hilbert 130 space \mathcal{H} , a suitable representation of an arbitrary density 131 operator $\rho \in \Omega_2$ is provided by 132

$$\rho = \frac{1}{2}(I + r_1\sigma_1 + r_2\sigma_2 + r_3\sigma_3)
= \frac{1}{2} \begin{pmatrix} 1 + r_3 & r_1 - ir_2 \\ r_1 + ir_2 & 1 - r_3 \end{pmatrix},$$
(1) 133

where σ_i are the Pauli matrices. This expression is useful 134 when providing a geometrical representation of ρ . Indeed, 135 each density operator $\rho \in \Omega_2$ can be geometrically rep-136 resented as a point of a radius-one sphere centered in the 137 origin (the so-called Bloch sphere), whose coordinates (i.e., 138 *Pauli components*) are r_i (with $\sum_i r_i^2 \leq 1$). By using the 139 generalized Pauli matrices (Bertlmann and Krammer 2008; 140 Kimura 2003), it is also possible to provide a geometrical 141 representation for an arbitrary n-dimensional density oper-142 ator, as it will be showed in Sect. 6. Again, by restricting 143 to a two-dimensional Hilbert space, points on the surface of 144 the Bloch sphere represent pure states, while inner points 145 represent mixed states. 146

Quantum formalism turns out to be very useful not only 147 in the microscopic scenario but also to encode classical 148

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data. This has naturally suggested several attempts to rep-149 resent the standard framework of machine learning through 150 the quantum formalism (Lloyd et al. 2013; Schuld et al. 151 2014a). In particular, pattern recognition (Webb and Copsey 152 2011; Duda et al. 2000) is the scientific discipline which 153 deals with theories and methodologies for designing algo-154 rithms and machines capable of automatically recognizing 155 "objects" (i.e., patterns) in noisy environments. Some typical 156 applications are multimedia document classification, remote-157 sensing image classification, and people identification using 158 biometrics traits such as fingerprints. 159

A pattern is a representation of an object. The object can 160 be a concrete one (i.e., an animal), and the pattern recognition 161 task could be to identify the kind of animal or an abstract one 162 (i.e., a facial expression), and the task could be to identify 163 the emotion expressed by the facial expression. The pattern is 164 characterized via a set of measurements called *features*.¹ Fea-165 tures can assume the forms of categories, structures, names, 166 graphs, or, most commonly, a vector of real numbers (feature 167 vector) $\mathbf{x} = (x_1, x_2, \dots, x_d) \in \mathbb{R}^d$. Intuitively, a class is the 168 set of all similar patterns. For the sake of simplicity, and with-169 out loss of generality, we assume that each object belongs to 170 one and only one class, and we will limit our attention to 171 two-class problems. For example, in the domain of "cats and 172 dogs," we can consider the classes C_{cats} (the class of all cats) 173 and C_{dogs} (the class of all dogs). The pattern at hand is either 174 a cat or a dog, and a possible representation of the pattern 175 could consist of the height of the pet and the length of its tail. 176 In this way, the feature vector $\mathbf{x_1} = (x_{11}, x_{12})$ is the pattern 177 representing a pet whose height and length of the tail are x_{11} 178 and x_{12} , respectively. 179

Now, let us consider an object \mathbf{x}_t whose membership class 180 is unknown. The basic aim of the classification process is 181 to establish which class \mathbf{x}_t belongs to. To achieve this goal, 182 standard pattern recognition designs a *classifier* that, given 183 the feature vector \mathbf{x}_t , has to determine the true class of the 184 pattern. The classifier should take into account all available 185 information about the task at hand (i.e., information about 186 the statistical distributions of the patterns and information 187 obtained from a set of patterns whose true class is known). 188 This set of patterns is called "training set," and it will be used 189 to define the behavior of the classifier. 190

If no information about the statistical distributions of the patterns is available, an easy classification algorithm that could
be used is the nearest mean classifier (NMC) (Manning et al.
2008; Hastie et al. 2001) or minimum distance classifier. The
NMC

- computes the centroids of each class, using the patterns on the training set $\mu_i^* = \frac{1}{n_i} \sum_{\mathbf{x} \in C_i} \mathbf{x}$, where n_i is the number of patterns of the training set belonging to the class C_i ;
- assigns the unknown pattern \mathbf{x}_t to the class with the closest centroid.

In the next section, we provide a representation of arbitrary 2D patterns by means of density matrices, while in Sect. 4, 203 we introduce a representation of NMC in terms of quantum objects. 205

3 Representation of two-dimensional patterns

Let $\mathbf{x_i} = (x_{i1}, \dots, x_{ik})$ be a generic pattern, i.e., a point in \mathbb{R}^k . 207 By means of this representation, we consider all the k features 208 of x_i as perfectly known. Therefore, x_i represents a maximal 209 kind of information, and its natural quantum counterpart is 210 provided by a pure state. For the sake of simplicity, we will 211 confine ourselves to an arbitary two-feature pattern indicated 212 by $\mathbf{x} = (x, y)$ ² In this section, a particular one-to-one corre-213 spondence between each pattern and its corresponding pure 214 density operator is provided. 215

The pattern **x** can be represented as a point in \mathbb{R}^2 . The stereographic projection (Coxeter 1969) allows to unequivocally map any point $r = (r_1, r_2, r_3)$ on the surface of a radius-one sphere \mathbb{S}^2 (except for the north pole) onto a point $\mathbf{x} = (x, y)$ of \mathbb{R}^2 as

$$SP: (r_1, r_2, r_3) \mapsto \left(\frac{r_1}{1 - r_3}, \frac{r_2}{1 - r_3}\right).$$
 (2) 221

The inverse of the stereographic projection is given by

$$SP^{-1}: (x, y) \mapsto \left(\frac{2x}{x^2 + y^2 + 1}, \frac{2y}{x^2 + y^2 + 1}, \frac{x^2 + y^2 - 1}{x^2 + y^2 + 1}\right).$$
(3) 223

Therefore, by using the Bloch representation given by Eq. (1) 224 and placing 225

$$r_1 = \frac{2x}{x^2 + y^2 + 1}, \quad r_2 = \frac{2y}{x^2 + y^2 + 1},$$
 226

$$r_3 = \frac{x^2 + y^2 - 1}{x^2 + y^2 + 1},\tag{4}$$

we obtain the following definition.

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¹ Hence, as a pattern is an object characterized by the knowledge of its features, analogously, in quantum mechanics a state of a physical system is represented by a density operator, characterized by the knowledge of its observables.

 $^{^2}$ In the standard pattern recognition theory, the symbol *y* is generally used to identify the label of the pattern. In this paper, for the sake of simplicity, we agree with a different notation.

Definition 1 (*Density pattern*) Given an arbitrary pattern 220 $\mathbf{x} = (x, y)$, the density pattern (DP) $\rho_{\mathbf{x}}$ associated with \mathbf{x} 230 is the following pure density operator 231

$$\rho_{\mathbf{x}} = \frac{1}{2} \begin{pmatrix} 1+r_3 & r_1 - ir_2 \\ r_1 + ir_2 & 1 - r_3 \end{pmatrix}$$
$$= \frac{1}{x^2 + y^2 + 1} \begin{pmatrix} x^2 + y^2 & x - iy \\ x + iy & 1 \end{pmatrix}.$$
(5)

It is easy to check that $tr(\rho_x^2) = 1$. Hence, ρ_x always represents a pure state for any value of the features x and y. 235

Following the standard definition of the Bloch sphere, it can 236 be verified that $r_i = tr(\rho_x \cdot \sigma_i)$, with $i \in \{1, 2, 3\}$ and σ_i are 237 Pauli matrices. 238

Example 1 Let us consider the pattern $\mathbf{x} = (1, 3)$. The cor-239 responding $\rho_{\mathbf{x}}$ reads 240

$$\rho_{\mathbf{x}} = \frac{1}{11} \begin{pmatrix} 10 & 1-3i \\ 1+3i & 1 \end{pmatrix}.$$

One of the advantages of this encoding is based on the 242 fact that it allows an easy visualization of an arbitrary two-243 feature dataset on the Bloch sphere, as it will be showed in 244 the next section. The manner to encode a real pattern onto 245 the space of the density operators is not unique and there 246 is a risk of losing some information during the encoding. 247 Taking into account the recent debates (Schuld et al. 2014a; 248 Lloyd et al. 2013; Rebentrost et al. 2014), in order to encode 249 a real vector to a quantum states without losing information. 250 it is necessary to normalize the vector but maintain some 251 information about the norm of the same vector at the same 252 time. By following this procedure, we briefly show that it is 253 alternatively possible to recover the stereographic encoding 254 proposed in Eq. (5) also by simple analytical considerations. 255 Let $\mathbf{x} = (x, y)$ be an arbitrary real vector. 256

- 1. First, we map \mathbf{x} onto a vector \mathbf{x}' whose first component 257 is given by x + iy and the second component is given 258 by the norm of $\mathbf{x} (|\mathbf{x}| = \sqrt{x^2 + y^2})$; i.e., $\mathbf{x} = (x, y) \mapsto \mathbf{x}' = (x + iy, \sqrt{x^2 + y^2})$. 259
- 260
- 2. Now, we consider a second map: $\mathbf{x}' \mapsto \mathbf{x}'' = \left(\frac{x+iy}{\sqrt{x^2+y^2}}, \sqrt{x^2+y^2}\right)$, obtained by normalizing the first 261 262 component of \mathbf{x}' . 263
- 3. Then, we consider the norm of \mathbf{x}'' , i.e., $|\mathbf{x}''| =$ 264 $\sqrt{x^2 + y^2 + 1}$ and we normalize the vector \mathbf{x}'' , i.e., $\mathbf{x}'' \mapsto$ 265

266
$$\mathbf{x}''' = \frac{\mathbf{x}''}{|\mathbf{x}''|} = \left(\frac{x+iy}{\sqrt{(x^2+y^2)(x^2+y^2+1)}}\right)$$

267 $\sqrt{\frac{x^2+y^2}{x^2+y^2+1}}$.

4. Now, we consider the projector: $\mathbb{P} = \mathbf{x}^{\prime\prime\prime} \cdot (\mathbf{x}^{\prime\prime\prime})^{\dagger} = \frac{1}{x^2 + y^2 + 1} \begin{pmatrix} 1 & x + iy \\ x - iy & x^2 + y^2 \end{pmatrix}.$ 268 269

5. Finally, we apply the operator $Not = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ to \mathbb{P} and we recover: $Not(\mathbb{P}) = \frac{1}{x^2 + y^2 + 1} \begin{pmatrix} x^2 + y^2 & x - iy \\ x + iy & 1 \end{pmatrix}$, that is 270 271 the same expression of the density pattern ρ_x introduced 272 in Eq (5). 273

The introduction of the density pattern leads to two differ-274 ent developments. The first one is shown in the next section 275 and consists of the representation of the NMC in quantum 276 terms. Moreover, in Sect. 5, starting from the framework of 277 density patterns, it will be possible to introduce a quantum 278 classifier that exhibits an improvement in the performance (in 279 terms of decreasing of the error in the classification process) 280 with respect to the NMC. 281

4 Classification process for density patterns

As introduced in Sect. 2, the NMC is based on the computa-283 tion of the minimum Euclidean distance between the pattern 284 to classify and the centroids of each class. In the previous 285 section, a quantum counterpart of an arbitrary (two feature) 286 "classical" pattern was provided. In order to obtain a quan-287 tum counterpart of the standard classification process, we 288 need to provide a suitable definition of distance d between 289 DPs. In addition to satisfy the standard conditions of met-290 ric, the distance d also needs to satisfy the preservation of 291 the order: Given three arbitrary patterns a, b, c such that 292 $d_E(a, b) \leq d_E(b, c)$, if ρ_a, ρ_b, ρ_c are the DPs related to 293 a, b, c, respectively, then $d(\rho_a, \rho_b) \leq d(\rho_b, \rho_c)$. In order to 294 fulfill all the previous conditions, we obtain the following 295 definition. 296

Definition 2 (Normalized trace distance) The normalized 297 trace distance \overline{d}_{tr} between two arbitrary density patterns ρ_a 298 and ρ_h is given by formula 299

$$\overline{d}_{tr}(\rho_a, \rho_b) = K_{a,b} d_{tr}(\rho_a, \rho_b), \qquad (6) \quad {}_{300}$$

where $d_{tr}(\rho_a, \rho_b)$ is the standard trace distance, $d_{tr}(\rho_a, \rho_b) =$ 301 $\frac{1}{2}\sum_{i} |\lambda_{i}|$, with λ_{i} representing the eigenvalues of $\rho_{a} - \rho_{b}$ 302 (Barnett 2009; Nielsen and Chuang 2000), and $K_{a,b}$ is a normalization factor given by $K_{a,b} = \frac{2}{\sqrt{(1-r_{a_3})(1-r_{b_3})}}$, with r_{a_3} 303 304 and r_{b_3} representing the third Pauli components of ρ_a and 305 ρ_b , respectively. 306

Proposition 1 Given two arbitrary patterns $a = (x_a, y_a)$ 307 and $b = (x_b, y_b)$ and their respective density patterns, ρ_a 308 and ρ_b , we have that 309

$$\overline{d}_{tr}(\rho_a, \rho_b) = d_E(a, b). \tag{7}$$

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³¹¹ *Proof* It can be verified that the eigenvalues of the matrix ³¹² $\rho_a - \rho_b$ are given by

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$$(\rho_a - \rho_b) = \pm \frac{d_E(a, b)}{\sqrt{(1 + x_a^2 + y_a^2)(1 + x_b^2 + y_b^2)}}.$$
 (8)

³¹⁴ Using the definition of trace distance, we have

³¹⁵
$$\operatorname{tr}\sqrt{(\rho_a - \rho_b)^2} = \frac{d_E(a, b)}{\sqrt{(1 + x_a^2 + y_a^2)(1 + x_b^2 + y_b^2)}}.$$
 (9)

By applying formula (4) to both r_{a_3} and r_{b_3} , we obtain that

$$K_{a,b} = \frac{2}{\sqrt{(1 - r_{a_3})(1 - r_{b_3})}} = \sqrt{(1 + x_a^2 + y_a^2)(1 + x_b^2 + y_b^2)}.$$
(10)

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Using Proposition 1, one can see that the normalized trace distance \overline{d}_{tr} satisfies the standard metric conditions and the preservation of the order.

Due to the computational advantage of a quantum algorithm able to faster calculate the Euclidean distance (Wiebe et al. 2015), the equivalence between the normalized trace distance and the Euclidean distance turns out to be potentially beneficial for the classification process we are going to introduce.

Let us now consider two classes, C_A and C_B and the 328 respective centroids³ $a^* = (x_a, y_a)$ and $b^* = (x_b, y_b)$. The 329 classification process based on NMC consists of finding the 330 space regions given by the points closest to the first centroid 331 a^* or to the second centroid b^* . The patterns belonging to 332 the first region are assigned to the class C_A , while patterns 333 belonging to the second region are assigned to the class C_B . 334 The points equidistant from both the centroids represent the 335 discriminant function (DF), given by 336

$$f_{\rm DF}(x, y) = 2(x_a - x_b)x + 2(y_a - y_b)y + (|b^*|^2 - |a^*|^2) = 0.$$
(11)

Thus, an arbitrary pattern c = (x, y) is assigned to the class C_A (or C_B) if $f_{DF}(x, y) > 0$ (or $f_{DF}(x, y) < 0$).

Let us notice that the Eq. (11) is obtained by imposing the equality between the Euclidean distances $d_E(c, a^*)$ and $d_E(c, b^*)$. Similarly, we obtain the quantum counterpart of the classical discriminant function. **Proposition 2** Let ρ_{a^*} and ρ_{b^*} be the DPs related to the centroids a^* and b^* , respectively. Then, the quantum discriminant function (QDF) is defined as

$$f_{\text{QDF}}(r_1, r_2, r_3) = \mathbf{F}(r_{a^*}, r_{b^*})^T \cdot \mathbf{r} + \tilde{K}^2 - 1 = 0$$
(12) 347

where $\mathbf{r} = (r_1, r_2, r_3), \{r_{a_i^*}\}, \{r_{b_i^*}\}$ are Pauli components of ρ_{a^*} and ρ_{b^*} , respectively, $\tilde{K} = \tilde{K}(r_{a_3^*}, r_{b_3^*}) = \frac{K_{c,a^*}}{K_{c,b^*}} = 349$ $\sqrt{\frac{1-r_{a_3^*}}{1-r_{b_3^*}}}, \mathbf{F}(r_{a^*}, r_{b^*}) = (r_{a_1^*} - \tilde{K}^2 r_{b_1^*}, r_{a_2^*} - \tilde{K}^2 r_{b_2^*}, r_{a_3^*} - 350$ $\tilde{K}^2 r_{b_3^*}).$

Proof In order to find the QDF, we use the equality between the normalized trace distances $K_{c,a}*d_{tr}(\rho_c, \rho_{a}*)$ and $K_{c,b}*d_{tr}(\rho_c, \rho_{b}*)$, where ρ_c is a generic DP with Pauli components r_1, r_2, r_3 . We have

$$K_{c,a^*} d_{\mathrm{tr}}(\rho_c, \rho_{a^*}) = \sqrt{\frac{(r_1 - r_{a_1^*})^2 + (r_2 - r_{a_2^*})^2 + (r_3 - r_{a_3^*})^2}{(1 - r_{a_3^*})(1 - r_3)}},$$

$$K_{c,b^*} d_{\mathrm{tr}}(\rho_c, \rho_{b^*}) = \sqrt{\frac{(r_1 - r_{b_1^*})^2 + (r_2 - r_{b_2^*})^2 + (r_3 - r_{b_3^*})^2}{(1 - r_{b_3^*})(1 - r_3)}}.$$
(13) 356

The equality $K_{c,a^*} d_{tr}(\rho_c, \rho_{a^*}) = K_{c,b^*} d_{tr}(\rho_c, \rho_{b^*})$ reads 357

$$\sum_{i=1}^{3} r_i^2 + \sum_{i=1}^{3} r_{a_i^*}^2 - 2\sum_{i=1}^{3} r_i r_{a_i^*}$$
 358

$$=\frac{1-r_{a_3^*}}{1-r_{b_3^*}}\left(\sum_{i=1}^3 r_i^2 + \sum_{i=1}^3 r_{b_i^*}^2 - 2\sum_{i=1}^3 r_i r_{b_i^*}\right).$$
(14) 356

In view of the fact that ρ_{a^*} , ρ_{b^*} and ρ_c are pure states, we use the conditions $\sum_{i=1}^{3} r_{a_i^*}^2 = \sum_{i=1}^{3} r_{b_i^*}^2 = \sum_{i=1}^{3} r_i^2 = 1$ and we get

$$\sum_{i=1}^{3} \left(r_{a_i^*} - \frac{1 - r_{a_3^*}}{1 - r_{b_3^*}} r_{b_i^*} \right) r_i + \frac{1 - r_{a_3^*}}{1 - r_{b_3^*}} - 1 = 0.$$
(15) 363

□ 364

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This completes the proof.

Similarly to the classical case, we assign the DP ρ_c 366 to the class C_A (or C_B) if $f_{\text{QDF}}(r_1, r_2, r_3) > 0$ (or 367 $f_{\text{QDF}}(r_1, r_2, r_3) < 0$). Geometrically, Eq. (12) represents 366 the surface equidistant from the DPs ρ_{a^*} and ρ_{b^*} . 369

Let us remark that, if we express the Pauli components $\{r_{a_i^*}\}, \{r_{b_i^*}\}$ and $\{r_i\}$ in terms of classical features by Eq. (4), then Eq. (12) exactly corresponds to Eq. (11). As a consequence, given an arbitrary pattern c = (x, y), if $f_{DF}(c) > 373$ 0 (or $f_{DF}(c) < 0$), then its relative DP ρ_c will satisfy 374 $f_{ODF}(\rho_c) > 0$ (or $f_{ODF}(\rho_c) < 0$, respectively). 375

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³ Let us remark that, in general, a^* and b^* do not represent true centroids, but centroids estimated on the training set.

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As an example, the comparison between the classical and quantum discrimination functions for the *Moon* dataset (composed of 200 patterns equally allocated in two classes) is made in Fig. 1. Plots in Fig. 1a, b present the classical and quantum discrimination, respectively.

It is worth noting that the correspondence between the pattern expressed as a feature vector (according to the standard 382 pattern recognition approach) and the pattern expressed as 383 a density operator is quite general. Indeed, it is not related 384 to a particular classification algorithm (NMC, in the previ-385 ous case) nor to the specific metric at hand (the Euclidean 386 one). Therefore, it is possible to develop a similar correspon-387 dence by using other kinds of metrics and/or classification 388 algorithms, different from NMC, adopting exactly the same 389 approach. 390

This result suggests potential developments which con-391 sist of finding a quantum algorithm able to implement the 392 normalized trace distance between density patterns. So, it 393 would correspond to implement the NMC on a quantum com-394 puter with the consequent well-known advantages (Wiebe 395 et al. 2015). The next section is devoted to the exploration 396 of another development that consists of using the framework of density patterns in order to introduce a "purely" quantum classification process (having no direct classical correspondence) called QC. It can be considered as a quantum-inspired version of the classical NMC because it substantially is a minimum distance classifier among quantum objects. The main difference between them, as we will show by numerical sim-403 ulations, is that the NMC is a linear classifier which does not 404 take into account the data dispersion, while the QC is not lin-405 ear, and conversely, it seems sensitive to the data dispersion. 406 As it will be showed in the next section by involving some 407 datasets, this fact seems to be particularly beneficial (with 408 respect to the NMC) mostly in the cases where the classes 409 are quite mixed, and hence, the NMC generates a consider-410 able error. 411

412 **5** Quantum classification procedure

In Sect. 4, we have shown that the NMC can be expressed by 413 means of quantum formalism, where each pattern is replaced 414 by a corresponding density pattern and the Euclidean distance 415 is replaced by the normalized trace distance. Representing 416 classical data in terms of quantum objects seems to be par-417 ticularly promising in quantum machine learning. Quoting 418 Lloyd et al. (2013) "Estimating distances between vectors 419 in N-dimensional vector spaces takes time O(log N) on 420 a quantum computer. Sampling and estimating distances 421 between vectors on a classical computer is apparently expo-422 nentially hard". This convenience has already been exploited 423 in machine learning for similar tasks (Wiebe et al. 2015; Gio-424 vannetti et al. 2008). Hence, finding a quantum algorithm for

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pattern classification using the proposed encoding could be
particularly beneficial to speed up the classification process
and it can suggest interesting developments. However, they
are beyond the scope of this paper.426
427

What we propose in this section is to exhibit some explicative examples to show how, on a classical computer, our classification procedure, based on the minimum distance, gives additional information with respect to the standard NMC.

5.1 Description of the quantum classifier (QC)

In order to get a real advantage in the classification process, 436 we need to be not confined in a pure representation of the 437 classical procedure in quantum terms. For this reason, we 438 introduce a purely quantum representation where we con-439 sider a new definition of centroid. The basic idea is to define 440 a quantum centroid not as the stereographic projection of the 441 classical centroid, but as a convex combination of density 442 patterns. 443

Trivially, given two real points x and y, the point z =444 $\frac{1}{2}(x+y)$ has the property to minimize the quantity $d_E(x, z)$ + 445 $d_E(z, y)$. In this case, $d_E(x, z) = d_E(z, y) = \frac{1}{2}d_E(x, y)$. 446 Similarly, let us consider two density operators ρ and σ 447 and let $\tau = \frac{1}{2}(\rho + \sigma)$. It is straightforward to show that 448 $d_{\rm tr}(\rho,\tau) = d_{\rm tr}(\tau,\sigma) = \frac{1}{2}d_{\rm tr}(\rho,\sigma)$. In fact, $d_{\rm tr}(\rho,\tau) =$ 449 $d_{\rm tr}(\rho, \frac{1}{2}(\rho + \sigma)) = \frac{1}{2} \sum |\tilde{\rm Eigenvalues}(\rho - \frac{1}{2}\rho - \frac{1}{2}\sigma)| =$ 450 $\frac{1}{2}\sum |\bar{\text{Eigenvalues}}(\frac{1}{2}(\rho - \sigma))| = \frac{1}{2} \cdot \frac{1}{2}\sum |\text{Eigenvalues}(\rho - \sigma)|$ 451 σ)| = $\frac{1}{2}d_{\rm tr}(\rho,\sigma)$. Analogously, we prove that $d_{\rm tr}(\sigma,\tau)$ = 452 $\frac{1}{2}d_{\rm tr}(\rho,\sigma).$ 453

Following this argument, we reasonably introduce the following definition.

Definition 3 (*Quantum centroid*) Given a dataset $\{P_1, \ldots, P_n\}$ with $P_i = (x_i, y_i)$, let us consider the respective set of density patterns $\{\rho_1, \ldots, \rho_n\}$. The Quantum centroid is defined as:

$$\rho_{QC} = \frac{1}{n} \sum_{i=1}^{n} \rho_i.$$
 460

Obviously, the reasonable ways to define a quantum version 461 of the classical centroid are not unique. We accord with this 462 definition because, as we show in the rest of the section, it 463 turns out to be beneficial in the reduction of the error during 464 some typical classification process. The reasons of this con-465 venience are intuitively contained in the following argument. 466 Let us notice that ρ_{OC} is a mixed state that does not have any 467 counterpart in the standard pattern recognition. Indeed, the 468 quantum centroid may include some further information that 469 the classical centroid generally discards. In fact, the classical 470 centroid does not involve all the information about the disper-471 sion of a given dataset, i.e., the classical centroid is invariant 472

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-10 -0.5 -10 -0.5 -10 -0.5 -1.0 (b)

Fig. 1 Comparison between the discrimination procedures for the *Moon* dataset in \mathbb{R}^2 (a) and in the Bloch sphere \mathbb{S}^2 (Banana). *Green* and *blue points* represent the two classes in the real space and in the Bloch sphere, respectively. The *straight line* in **b** represents the classical

under uniform scaling transformations of the data. Consequently, the classical centroid does not take into account any
dispersion phenomena. Standard pattern recognition compensates for this lack by involving the covariance matrix
(Duda et al. 2000).

On the other hand, the quantum centroid is not invariant
under uniform scaling. In what follows, we show how the
general expression of the quantum centroid is dependent on
an arbitrary rescaling of a given dataset.

Let us consider the set of *n* points $\{P_1, \ldots, P_n\}$, where 482 $P_i = (x_i, y_i)$ and let $C = (c_x, c_y) = (\frac{1}{n} \sum_{j=1}^n x_j)$ 483 $\frac{1}{n}\sum_{i=1}^{n} y_i$ be the respective classical centroid. A uniform 484 rescaling of n points of the dataset corresponds to move 485 each point P_i along the line joining itself with C, whose 486 generic expression is given by: $y_{x_i} = \frac{x - c_x}{x_i - c_x}(y_i - c_y) + c_y$. 487 Let $\tilde{P}_i = (\tilde{x}_i, y_{\tilde{x}_i})$ be a generic point on this line. Obviously, 488 a uniform rescaling of P_i by a real factor α is represented by 489 the map: $\tilde{P}_i = (\tilde{x}_i, y_{\tilde{x}_i}) \mapsto \alpha \tilde{P}_i = (\alpha \tilde{x}_i, y_{\alpha \tilde{x}_i})$. Even if the 490 classical centroid is not dependent on the rescaling factor α , 491 on the other hand the expression of the quantum centroid is: 492

$$\mu_{493} \quad \rho_{QC} = \frac{1}{n} \left(\sum_{i=1}^{n} \frac{(\alpha \tilde{x}_{i})^{2} + (y_{\alpha \tilde{x}_{i}})^{2}}{(\alpha \tilde{x}_{i})^{2} + (y_{\alpha \tilde{x}_{i}})^{2} + 1} \sum_{i=1}^{n} \frac{\alpha \tilde{x}_{i} - iy_{\alpha \tilde{x}_{i}}}{(\alpha \tilde{x}_{i})^{2} + (y_{\alpha \tilde{x}_{i}})^{2} + 1} \sum_{i=1}^{n} \frac{\alpha \tilde{x}_{i} - iy_{\alpha \tilde{x}_{i}}}{(\alpha \tilde{x}_{i})^{2} + (y_{\alpha \tilde{x}_{i}})^{2} + 1} \sum_{i=1}^{n} \frac{\alpha \tilde{x}_{i} - iy_{\alpha \tilde{x}_{i}}}{(\alpha \tilde{x}_{i})^{2} + (y_{\alpha \tilde{x}_{i}})^{2} + 1} \right)$$

494 that, clearly, is dependent on α .

According to the same framework used in Sect. 4, given two classes C_A and C_B of real data, let ρ_{QCa} and ρ_{QCb}

discriminant function given by (11); on the other hand, the plane that intersects the Bloch sphere in **b** represents the quantum discriminant function given by (12)

be the respective quantum centroids. Given a pattern P497 and its respective density pattern, ρ_P , P is assigned to 498 the class C_A (or C_B) if $d_{tr}(\rho_P, \rho_{QCa}) < d_{tr}(\rho_P, \rho_{QCb})$ 499 (or $d_{tr}(\rho_P, \rho_{OCa}) > d_{tr}(\rho_P, \rho_{OCb})$, respectively). Let us 500 remark that we no longer need any normalization parame-501 ter to be added to the trace distance d_{tr} , because the exact 502 correspondence with the Euclidean distance is no more a nec-503 essary requirement in this framework. From now on, we refer 504 to the classification process based on density patterns, quan-505 tum centroids, and trace distances as the *Quantum Classifier* 506 (QC). 507

We have shown that the quantum centroid is not indepen-508 dent from the dispersion of the patterns and it could contain 509 some additional information with respect to the classical cen-510 troid. Consequently, it is reasonable to expect that in different 511 cases QC could provide some better performance than the 512 NMC. The next subsection will be devoted to the exploita-513 tion of the difference between the classification procedures 514 by means of numerical simulations on different datasets. 515 Before presenting the experimental results, let us briefly 516 introduce the main statistical indices widely used to evaluate 517 the performance of a supervised learning algorithm. 518

In particular, for each class, it is typical to refer to the respective confusion matrix (Fawcet 2006). It is based on four possible kinds of outcome after the classification of a certain pattern:

- True positive (TP): pattern correctly assigned to its class;
- True negative (TN): pattern correctly assigned to another class; 524

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- False positive (FP): pattern uncorrectly assigned to its class;
- False negative (FN): pattern uncorrectly assigned to another class.

According to above, it is possible to recall the following definitions use to evaluate the performance of an algorithm.⁴

True positive rate (TPR), or sensitivity or recall: TPR = $\frac{TP}{TP+FN}$; false positive rate (FPR): FPR = $\frac{FP}{FP+TN}$; true negative rate (TNR): TNR = $\frac{TN}{TN+FP}$; false negative rate (FNR): FNR = $\frac{FN}{FN+TP}$.

Let us consider a dataset of *C* elements allocated in *m* different classes. We also recall the following basic statistical notions:

- Error:
$$E = 1 - \frac{\text{TP} + \text{TN}}{C}$$
;
- Precision: $\text{Pr} = \frac{\text{TP}}{\text{TP} + \text{FP}}$.

Moreover, another statistical index that is very useful to indicate the reliability of a classification process is given by the Cohen's k, that is $k = \frac{\Pr(a) - \Pr(e)}{1 - \Pr(e)}$, where $\Pr(a) = \frac{\text{TP+TN}}{C}$ and $\Pr(e) = \frac{(\text{TP+FP})(\text{TP+FN}) + (\text{FP+TN})(\text{TN+FN})}{C^2}$. The value of k is such that $-1 \le k \le 1$, where the case k = 1 corresponds to a perfect classification procedure and the case k = -1corresponds to the worst classification procedure.

548 5.2 Implementing the quantum classifier

In this subsection, we implement the QC on different datasets
and show the difference between QC and NMC in terms of the
values of error, accuracy, precision, and other probabilistic
indices summarized above.

We will show how our quantum classification procedure
 exhibits partial or significant convenience with respect to the
 NMC on a classical computer.

In particular, we consider four datasets: Two of them (following Gaussian distributions) called *Gaussian* and *3Class-Gaussian*, where the first one is composed of 200 patterns allocated in two classes and the second one is composed of 450 patterns allocated in three classes, and the other two, called *Moon* and *Banana*, composed of 200 and 5300 patterns (respectively) allocated in two different classes.

The experiments have been conducted by randomly subdividing each dataset into a training set made up of 80% of instances and a test set containing the remaining instances. The results are reported in terms of averages of the computed statistical indices over 100 runs of the experiments.

We denote the variables listed in the tables as follows: E =Error; $E_i =$ Error on the class i; Pr = Precision; k = Cohen's

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k; TPR = True positive rate; FPR = False positive rate; TNR = 570 True negative rate; FNR = False negative rate. Let us remark 571 that i) the values listed in the table are referred to the mean 572 values over the classes; *ii*) in the case where the number of the 573 classes is equal to two, a pattern that is correctly classified as 574 belonging to a class corresponds to a pattern that is correctly 575 classified as not belonging to the other class; on this basis, 576 the mean value of TPR is equal to the mean value of TNR. 577 and similarly, the mean value of FPR is equal to the mean 578 value of FNR. 579

In order to provide a complete visualization of the difference between the two classification procedures, we also represent in the figures below the results of both classifications by considering the whole dataset for both training and test dataset.⁵

We stress that for some of the following datasets, the NMC is clearly not the optimal classifier and there exist classifiers that overcome it in terms of accuracy and performance. However, our aim in this context is confined the comparison of two minimum distance classifiers (classical and quantuminspired version) trying to capture the main differences. 590

5.2.1 Gaussian dataset

This dataset consists of 200 patterns allocated in two classes (of equal size), following Gaussian distributions whose means are $\mu_1 = (1, 1), \mu_2 = (2, 2)$ and covariance matrices are $\Sigma_1 = \text{diag}(20, 50), \Sigma_2 = \text{diag}(5, 5)$, respectively. 595

As depicted in Fig. 2, the classes appear particularly over-596 lapped and the OC is able to classify a number of true positive 597 patterns that is significantly larger than the NMC. Hence, see 598 Table 1, the error of the QC is (about 20%) smaller than 599 the error of the NMC. In particular, the QC turns out to be 600 strongly beneficial in the classification of the patterns of the 601 second class. Moreover, the values related to accuracy, pre-602 cision, and the other statistical indices also exhibit relevant 603 improvements with respect to the NMC.⁶ 604

5.2.2 The 3ClassGaussian dataset

In this example, we consider an equally distributed threeclass dataset, consisting of 450 patterns. The classes are distributed as Gaussian random variables whose means are $\mu_1 = (-3, -3), \mu_2 = (5, 5), \mu_3 = (7, 7)$ and covariance matrices are $\Sigma_1 = \text{diag}(50, 100), \Sigma_2 = \text{diag}(10, 5), \text{ and}$ $\Sigma_3 = \text{diag}(30, 70),$ respectively.

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⁴ For the sake of the simplicity, from now on, we indicate $\sum_{j=1}^{C} \text{TP}_{j}$ with TP. Similarly for TN, FP, and FN.

⁵ This make sense because it can be seen that for all the datasets we deal with, the classification error is very similar both with and without splitting training and test sets.

⁶ Let us remark that there are some patterns correctly classified by the NMC which are neglected by the QC. On this basis, exploiting their complementarity, in principle it also makes sense to consider a combination of both classifiers.



Fig. 2 Experimental results obtained for the Gaussian dataset: a dataset used in the experiments, b classification obtained using NMC, c classification obtained using QC

Table 1 Gaussian dataset		E	<i>E</i> 1	<i>E</i> 2	Pr	k	TPR	FPR
	NMC	0.457 ± 0.065	0.409 ± 0.108	0.503 ± 0.096	0.544	0.085	0.544	0.456
	QC	0.246 ± 0.064	0.291 ± 0.096	0.203 ± 0.088	0.756	0.502	0.753	0.247

As for the two-class Gaussian dataset, the three classes appear quite overlapped, and once again, the computation of the error and the other statistical indices evaluated for both QC and NMC shows that the first one is more convenient especially for the classification of the first- and second-class patterns (Table 2).⁷

5.2.3 The Moon dataset

This dataset consists of 200 patterns equally distributed in
two classes. In this case, we observe a mean error reduction
of about 4%. In particular, the classification error related to
the second class is very similar for both NMC and QC, while
we can note that the QC turns out to be particularly beneficial
in the classification of the first-class patterns (for which the
error decreases by about 10%).619619620

 $^{^7}$ In this case, by combining QC and NMC together, the mean error decreases up to about 0.247 (±4.280).

Table 2 3Gaussian dataset

	Ε	<i>E</i> 1	<i>E</i> 2	E3	Pr	k	TPR	FPR	TNR	FNR
NMC	0.358 ± 0.046	0.385 ± 0.085	0.422 ± 0.094	0.272 ± 0.077	0.651	0.462	0.640	0.179	0.821	0.360
QC	0.288 ± 0.045	0.296 ± 0.097	0.310 ± 0.084	0.259 ± 0.083	0.723	0.567	0.712	0.144	0.856	0.288

626 5.2.4 The Banana dataset

The Banana dataset presents a particularly complex distri-627 bution that is very hard to deal with the NMC. Indeed, the 628 classification error we get by using the NMC is high and 629 we would not use it in practice. Anyway, as we have already 630 explained, we consider this particular dataset in order to show 631 the substantial difference between two approaches (i.e., min-632 imum distance classifiers) having the same nature (Fig. 3; 633 Table 3). 634

This dataset consists of 5300 patterns unequally distributed between the two classes (2376 patterns belonging to the first class and 2924 belonging to the second one). In this case, the QC turns out to be beneficial in terms of all statistical indices and for both classes⁸ it exhibits a mean error reduction of about 3% (Figs. 4, 5; Table 4).

Let us notice that, in accordance with the well known No 641 Free Lunch Theorem (Duda et al. 2000), even if the previ-642 ous examples exhibit a (particular or partial) benefit of the 643 QC with respect to the NMC, in general there is no classi-644 fier whose performance is better than all the others for any 645 dataset. This paper is focused on the comparison between 646 the NMC and the QC because these methods are exclusively 647 based on the pattern-centroid distance. Anyway, a wide com-648 parison among the QC and other commonly used classifiers 649 (such as the LDA—Linear Discriminant Analysis—and the 650 QDA—Quadratic Discriminant Analysis) will be proposed 651 for future works, where also other quantum metrics (such as 652 the Fidelity, the Bures distance etc) instead of the trace dis-653 tance and alternative definitions of quantum centroids will 654 be considered to provide an adaptive version of the quantum 655 classifier. 656

657 6 Geometrical generalization of the model

In Sect. 3, we provided a representation of an arbitrary twofeature pattern **x** in terms of a point on the surface of the Bloch sphere \mathbb{S}^2 , i.e., a density operator $\rho_{\mathbf{x}}$. A geometrical extension of this model to the case of *n*-feature patterns inspired by quantum framework is possible. In this section, by generalizing the encoding proposed in Sect. 2, we introduce a method for representing an arbitrary *n*-dimensional real pattern as a point in the radius-one hypersphere \mathbb{S}^n , centered in the origin.

A quantum system described by a density operator ρ in an *n*-dimensional Hilbert space \mathcal{H} can be represented by a linear combination of the *n*-dimensional identity I and $n^2 - 1$ $(n \times n)$ -square matrices { σ_i } [i.e., generalized Pauli matrices (Bertlmann and Krammer 2008; Kimura 2003)]: 671

$$o = \frac{1}{n}I + \frac{1}{2}\sum_{i=1}^{n^2-1} r_i\sigma_i,$$
(16) 672

where the real numbers $\{r_i\}$ are the Pauli components of ρ . 673 Hence, by Eq. (16), a density operator ρ acting on an *n*-674 dimensional Hilbert space can be geometrically represented 675 as a $(n^2 - 1)$ -dimensional point $P = (r_1, r_2, \dots, r_{\tilde{n}})$ in 676 the Bloch hypersphere $\mathbb{S}^{\tilde{n}-1}$, with $\tilde{n} = n^2 - 1$. Therefore, 677 by using the generalization of the stereographic projection 678 (Karlığa 1996), we obtain the vector $\mathbf{x} = (x_1, x_2, \dots, x_{\tilde{n}-1})$ 679 that is the correspondent of P in \mathbb{R}^{n^2-2} . In fact, the general-680 ization of Eqs. (2-3) is given by 681

$$SP_{(\tilde{n})} : (r_1, r_2, \dots, r_{\tilde{n}}) \mapsto \left(\frac{r_1}{1 - r_{\tilde{n}}}, \frac{r_2}{1 - r_{\tilde{n}}}, \dots, \frac{r_{\tilde{n}-1}}{1 - r_{\tilde{n}}}\right)$$

$$= (x_1, x_2, \dots, x_{\tilde{n}-1})$$
(17) 663

$$SP_{(\tilde{n})}^{-1}:(x_1,x_2,\ldots,x_{\tilde{n}-1})$$

$$\mapsto \left(\frac{2x_1}{\sum_{i=1}^{\tilde{n}} x_i^2 + 1}, \dots, \frac{2x_{\tilde{n}-1}}{\sum_{i=1}^{\tilde{n}} x_i^2 + 1}, \frac{\sum_{i=1}^{\tilde{n}} x_i^2 - 1}{\sum_{i=1}^{\tilde{n}} x_i^2 + 1}\right)$$

$$= (r_1, r_2, \dots, r_{\tilde{n}}).$$

$$(18) \quad 68$$

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Hence, by Eq. (17), a two-dimensional density matrix is 687 determined by three Pauli components and it can be mapped 688 onto a two-dimensional real vector. Analogously, a three-689 dimensional density matrix is determined by eight Pauli 690 components and it can be mapped onto a seven-dimensional 691 real vector. Generally, an n-dimensional density matrix is 692 determined by $n^2 - 1$ Pauli components and it can be mapped 693 onto an $n^2 - 2$ -dimensional real vector. 694

Now, let consider an arbitrary vector $\mathbf{x} = (x_1, x_2, ..., x_m)$ 695 with $(n-1)^2 - 1 < m < n^2 - 2$. In this case, Eq. (18) cannot be applied because $m \neq n^2 - 2$. In order to represent *a* in an *n*-dimensional Hilbert space, it is sufficient to involve only m + 1 Pauli components (instead of all the $n^2 - 1$ Pauli components of the *n*-dimensional space). Hence, we need to

⁸ Similarly to the Gaussian case, also for the Banana dataset, the NMC is able to correctly classify some points unclassified by the QC. Indeed, by considering the combination of both classifiers, the mean error can decrease up to 10%.



Fig. 3 Experimental results obtained for the 3ClassGaussian dataset: a dataset used in the experiments, b classification obtained using NMC, c classification obtained using QC

	Е	<i>E</i> 1	<i>E</i> 2	Pr	k	TPR	FPR
NMC	0.211 ± 0.057	0.212 ± 0.094	0.210 ± 0.076	0.789	0.572	0.789	0.21
QC	0.174 ± 0.047	0.118 ± 0.075	0.226 ± 0.079	0.831	0.649	0.828	0.172

⁷⁰¹ project the Bloch hypersphere \mathbb{S}^{n^2-2} onto the hypersphere ⁷⁰² \mathbb{S}^m . We perform this projection by using Eq. (18) and by ⁷⁰³ assigning some fixed values to a number of Pauli components ⁷⁰⁴ equal to $n^2 - m - 2$. In this way, we obtain a representation ⁷⁰⁵ in \mathbb{S}^m that involves m + 1 Pauli components and it finally ⁷⁰⁶ allows the representation of an *m*-dimensional real vector.

Table 3 Moon dataset

Example 2 Let us consider a vector $\mathbf{x} = (x_1, x_2, x_3)$. By Eq. (18), we can map \mathbf{x} onto a vector $r_{\mathbf{x}} = (r_1, r_2, r_3, r_4) \in \mathbb{S}^3$. Hence, we need to consider a three-dimensional Hilbert space \mathcal{H} . Then, an arbitrary density operator $\rho \in \Omega_3$ can be written as

$$\rho = \frac{1}{3} \left(I + \sqrt{3} \sum_{i=1}^{8} r_i \sigma_i \right)$$
(19) 712

with $\{r_i\}$ Pauli components such that $\sum_{i=1}^{8} r_i^2 \leq 1$ and $\{\sigma_i\}$ 713 generalized Pauli matrices. In this case, $\{\sigma_i\}$ is the set of eight 714 3×3 matrices also known as *Gell-Mann matrices*, namely 715

$$\sigma_1 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \qquad {}^{716}$$

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Fig. 4 Experimental results obtained for the Moon dataset: a dataset used in the experiments, b classification obtained using NMC, c classification obtained using QC

	Ε	<i>E</i> 1	<i>E</i> 2	Pr	k	TPR	FPR
NMC	0.448 ± 0.0	017 0.425 ± 0.023	$8 0.466 \pm 0.02$	0.554	0.107	0.554	0.446
QC	0.419 ± 0.0	0.15 0.387 ± 0.022	$2 0.446 \pm 0.02$	0.583	0.165	0.584	0.416

$$\sigma_{4} = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad \sigma_{5} = \begin{pmatrix} 0 & 0 & -i \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix}, \quad \sigma_{6} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix},
\sigma_{7} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix}, \quad \sigma_{8} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}.$$
(20)

Consequently, the generic form of a density operator ρ in the three-dimensional Hilbert space is given by 721

$$\rho = \frac{1}{3} \begin{pmatrix} \sqrt{3}r_3 + r_8 + 1 & \sqrt{3}(r_1 - ir_2) & \sqrt{3}(r_4 - ir_5) \\ \sqrt{3}(r_1 + ir_2) & -\sqrt{3}r_3 + r_8 + 1 & \sqrt{3}(r_6 - ir_7) \\ \sqrt{3}(r_4 + ir_5) & \sqrt{3}(r_6 + ir_7) & 1 - 2r_8 \end{pmatrix}.$$
(21) 722

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Author Proof

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Table 4 Banana dataset

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Fig. 5 Experimental results obtained for the Banana dataset: a dataset used in the experiments, b classification obtained using NMC, c classification obtained using QC

Then, for any ρ , it is possible to associate an eightdimensional Bloch vector $r = (r_1, \ldots, r_8) \in \mathbb{S}^7$. However, by taking $r_j = 0$ for $j = 5, \ldots, 8$, we obtain

$$\rho_{\mathbf{x}} = \frac{1}{3} \begin{pmatrix} \sqrt{3}r_3 + 1 & \sqrt{3}(r_1 - ir_2) & \sqrt{3}r_4 \\ \sqrt{3}(r_1 + ir_2) & -\sqrt{3}r_3 + 1 & 0 \\ \sqrt{3}r_4 & 0 & 1 \end{pmatrix}$$
(22)

that, by Eq. (18), can be seen as a point projected in \mathbb{S}^3 , where

728
$$SP_{(4)}^{-1}(\mathbf{x}) = r_{\mathbf{x}}$$

729 $= \left(\frac{2x_1}{\sum_{i=1}^3 x_i^2 + 1}, \frac{2x_2}{\sum_{i=1}^3 x_i^2 + 1}, \frac{2x_3}{\sum_{i=1}^3 x_i^2 + 1}, \frac{\sum_{i=1}^3 x_i^2 - 1}{\sum_{i=1}^3 x_i^2 + 1}\right).$
730 (23)

The generalization introduced above allows the representa-731 tion of arbitrary patterns $\mathbf{x} \in \mathbb{R}^n$ as points $\rho_{\mathbf{x}} \in \mathbb{S}^n$ as a 732 natural extension of the encoding proposed in Sect. 2. Also, 733 the classification procedure introduced in Sect. 4 can be nat-734 urally extended for an arbitrary n-feature pattern where the 735 normalized trace distance between two DPs ρ_a and ρ_b can 736 be expressed using Eq. (17) in terms of the respective Pauli 737 components as 738

$$\overline{d}_{tr}(\rho_a, \rho_b) = \frac{\sqrt{\sum_{i=1}^{n} [(r_{a_i} - r_{b_i}) - (r_{a_i}r_{a_{n+1}} - r_{b_i}r_{a_{n+1}})]^2}}{(1 - r_{a_{n+1}})(1 - r_{b_{n+1}})}.$$
(24) 740

Analogously, also the QC could be naturally extended to a 741 *n*-dimensional problem (without loss of generality) by introducing a *n*-dimensional quantum centroid. 743

Author Proof

7 Conclusions and further developments 744

In this work, we have proposed a quantum-inspired version 745 (OC) of the nearest mean classifier (NMC) and we have 746 shown some convenience of the QC by comparing them 747 on different datasets. Firstly, we have introduced a one-to-748 one correspondence between two-feature patterns and pure 749 density operators by using the concept of *density patterns*. 750 Starting from this representation, firstly we have described 751 the NMC in terms of quantum objects by introducing an 752 ad hoc definition of normalized trace distance. We have 753 found a quantum version of the discrimination function by 754 means of Pauli components. The equation of this surface was 755 obtained by using the normalized trace distance between den-756 sity patterns. Geometrically, it corresponds to a surface that 757 intersects the Bloch sphere. This result could be potentially 758 useful because it suggests to find an appropriate quantum 759 algorithm able to provide a quantum version of the NMC in 760 a quantum computer, with a consequent significative reduc-761 tion in the computational complexity of the process (Lloyd 762 et al. 2013; Wiebe et al. 2015). 763

Secondly, a suitable definition of a quantum centroid that 764 does not have a classical direct correspondence permits to 765 introduce a quantum classifier, which can be considered as 766 a quantum-inspired version of the NMC, i.e., a minimum 767 distance classifier. 768

The main implementative result of the paper consists of 769 comparing the performance of NMC and QC on datasets with 770 different properties. In particular, we found out that the OC 771 may exhibit some better performance sensitive to the data 772 dispersion. Then, the QC seems to be promising for classi-773 fying datasets whose classes have mixed distributions more 774 difficult to treat by using the NMC. This also suggests to 775 compare the QC with other standard classifiers as a further 776 development. Further developments will be devoted to com-777 pare the QC with other commonly used classical classifiers. 778

- Finally, we have presented a generalization of our model 779 that allows to express arbitrary n-feature patterns as points 780 on the hypersphere S^n , obtained by using the generalized 78 stereographic projection. However, even if it is possible to 782 associate the points of a *n*-hypersphere to *n*-feature patterns, 783 these points do not generally represent density operators. In 784 Kimura (2003), Jakóbczyk and Siennicki (2001), Kimura and 785 Kossakowski (2005), the authors found some conditions that 786 guarantee the one-to-one correspondence between the points 787 on particular regions of the hypersphere and density matri-788 ces. A full development of our work is therefore intimately 789 connected to the study of the geometrical properties of the 790 generalized Bloch sphere. 79
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Compliance with ethical standards

Conflict of interest The authors declare that they have no conflict of interest.

Ethical approval This article does not contain any studies with human participants or animals performed by any of the authors.

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